# **HERON® MS TWIN Color**

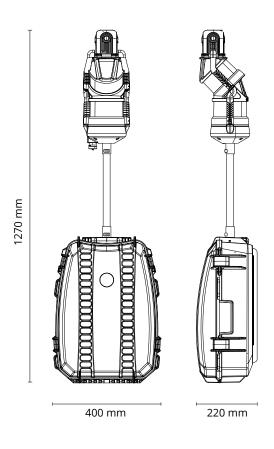
# **TECH SHEET**

## **MAIN FEATURES**

| Suitable environment  | indoor/outdoor                               |
|---|--|
| Handheld  | possible (1)                                 |
| Wearable  | yes  |
| Mountable on various mobile platforms (car, trolley, bike, quad, boat, robot)   | yes  |
| SLAM post-processing software included (HERON Desktop)                          | yes  |
| Point cloud advanced processing software included (Reconstructor)               | yes  |
| Free software for x-ray maps visualization and measuring included (GoBlueprint) | yes  |
| Output data   | .e57, .las, .ply,<br>export to ReCap         |
| Points per second   | 1,280,000                                    |
| Local accuracy  | ±4 mm  |
| Max survey resolution   | 1 cm   |
| Global accuracy   | ±2 cm in short<br>close rings <sup>(2)</sup> |
| Control points acquisition  | yes  |
| Global accuracy with control points   | ±1 cm  |
| Loop closure  | not mandatory                                |
| Usable in every light conditions  | yes  |
| Initialization and calibration procedures                                       | not required                                 |
| Single operator   | yes  |
| Sensors working time (in continuous acquisition)                                | ~ 1h 15min (more with extra batteries)       |
| Real-time visualization of RGB 8K images  | yes  |
| Change detection &<br>Automatic self-localization                               | yes (optional add-on)                        |
| Operating temperature   | -10°; +45°                                   |
| Storage temperature   | -40°; +60°                                   |
| Rugged transport case   | yes  |
|   |  |

# **CAPTURE HEAD** (DETACHABLE)

| Weight   Dimensions           | 3000 g   382 x 141 x 153 mm  |  |
|-------------------------------|------------------------------|--|
| COMPONENTS:                   |                              |  |
| • LASER SENSORS               | 32+32 chs   Class 1 Eye Safe |  |
| Laser wavelength              | 905 nm                       |  |
| Minimum laser range           | 0.05 m                       |  |
| Maximum laser range           | 300 m                        |  |
| FOV                           | 360° x 360° (3)              |  |
| • IMU                         | yes                          |  |
| • RGB PANO CAMERA (MG1)       | n. 1   4 lenses              |  |
| Continuous acquisition        | 24 Hz   4K Ultra HD          |  |
| Single shot acquisition       | 8K                           |  |
| FOV                           | 360°                         |  |
| Automatic color/light balance | yes                          |  |
| Automatic exposure control    | yes (4)                      |  |
|                               |                              |  |



## **SYSTEM CONTROLLER**

| Weight   Dimensions         | 1085 g   160 x 209 x 59 mm                                 |
|-----------------------------|--|
| Processor                   | Intel® 11 <sup>th</sup> Gen Core™ (4.1 GHz)                |
| • PENDRIVE for data storage | USB 3.1 Gen 1  |
| Memory size                 | 256 GB   |
| Max read speed              | up to 300 MB/sec   |
| Max write speed             | up to 100 MB/sec   |
| • INTERNAL BATTERY          | Li-ion battery   |
| Capacity                    | 6700 mAh   80.4 Wh   |
| Output                      | 12 V   |
| Working time                | ~ <b>1h 15min</b> (more with extra<br>"plug&go" batteries) |
|                             |  |

# **PDA CONTROL UNIT**

Personal Digital Assistant

| Weight   Dimensions  | 560 g   167 x 81.4 x 15.5 mm                      |
|----------------------|---|
| Processor            | Helio G95 Octa Core 2.1 GHz                       |
| Display              | 6.22" LCD HD + waterdrop screen                   |
| Battery              | Li-ion   6350 mAh                                 |
| Battery charging     | 24 W Type-C fast charge                           |
| Battery working time | 15 ÷ 24 h<br>(depending on the display intensity) |





## **TECH SHEET**

#### **RUGGED BACKPACK**

| Weight   Dimensions           | 4850 g   540 x 400 x 220 mm               |
|-------------------------------|---|
| Internally cabled             | Controller and Capture<br>Head connection |
| For mapping use               | yes                                       |
| For storage and transport use | yes                                       |

#### **OPTIONAL TOOLKITS**

| Extra batteries | standard   "plug&go"   ~ 1h 20min   445 g |
|-----------------|---|
| Telescopic pole | from 560 to 1800 mm   1000 g              |
| Centering tip   | 150 mm   12 g                             |
| Ring LED Light  | Ø126 x 184 mm   700 g   4000 lm   36 W    |
| Car mount       | (with case) 547 x 427 x 251 mm   9000 g   |

#### **SOFTWARE EQUIPMENT**

| Reconstructor  | included  |
|--|---|
| Reconstructor HERON add-on                               | included  |
| 3D navigation of point clouds and images                 | yes   |
| Automatic scans registration                             | yes   |
| Import   | TLS data, .ifc BIM,<br>point clouds from UAV,<br>mobile mapping data  |
| Direct import formats                                    | .laz, .e57, .fls, .zfs, .rxp, .x3s,<br>.x3m, .clr, .cl3, .dp, .ixf, .nctri,<br>.txt, .las, .ptx, .pts, .ptg, .asc,<br>.ply, .csv, DEM Ascii |
| Point cloud filtering, managing and classifying          | yes   |
| CAD/Mesh models  | .3ds, .ifc, .obj, .dxf, .stl, .txt,<br>.wrl, .vrml, .ply, .mvx, .dae  |
| Mesh creation and manipulation                           | yes   |
| Volumes and areas computation                            | yes   |
| Cross sections and profiles (.dxf)                       | yes   |
| Verification tool  | yes   |
| Orthophotos/x-Ray orthophotos (direct export to AutoCAD) | yes   |
| Direct export of 3D point clouds and 2D maps             | .las, .e57 with images,<br>ReCap, AutoCAD   |
| Cloud sharing  | AtisCloud, Benaco, Cintoo<br>Cloud, FARO Webshare,<br>Geo-Plus,TopconCollageWeb   |

| HERON Desktop                                   | included |
|---|----------|
| Drift effect reducing (global optimization)     | yes      |
| 3D local maps patented algorithm                | yes      |
| Large coordinates for geolocalization           | yes      |
| Split/merge trajectories and point clouds       | yes      |
| Automatic post-processing mode                  | yes      |
| Noise cleaning (attenuation)                    | yes      |
| Moving objects removing                         | yes      |
| Constraints tool (control points/control scans) | yes      |

| GoBlueprint   | free software |
|---|---------------|
| Measures on x-Ray maps directly (lines, angles, areas)                      | yes           |
| Volume calculation based on x-Ray maps                                      | yes           |
| For any Windows-based PC and tablet (to easily bring your maps on-site too) | yes           |
| Deliverables easy to manage and share                                       | yes           |

| Reconstructor 3D Viewer                      | free software |
|--|---------------|
| 3D model navigation and immersive tour at 8K | yes           |
|  |               |
| HERON Tracking add-on                        | optional      |
| Reconstructor MINING add-on                  | optional      |
| Reconstructor COLOR add-on                   | optional      |
| ClearEdge3D EdgeWise   Verity   Rithm        | optional      |
| Cintoo Cloud                                 | ontional      |

- (1) When needed, it is possible to use the capture head with telescopic poles, to easily map hidden areas such as holes, ravines, manholes, etc.
- (2) The global accuracy depends on the effectiveness of the SLAM registration algorithm, which can be influenced by the geometry of the surveyed environment. Long trajectories in absence of loop closures and cross paths, such as narrow tunnels or narrow stairs, can downgrade the global accuracy to 2-3 cm. The patented and unique algorithms present in HERON Desktop and the use of control points or control scans as constraints can dramatically improve the quality of the global accuracy up to 1 cm. The Gexcel support team is always available to provide you with more detailed information on this topic.
- (3) Final FOV guaranteed by walking with the system.
- (4) The camera may not perform optimally in dark places. In these cases, we suggest the use of the Ring LED Light optional kit.

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