

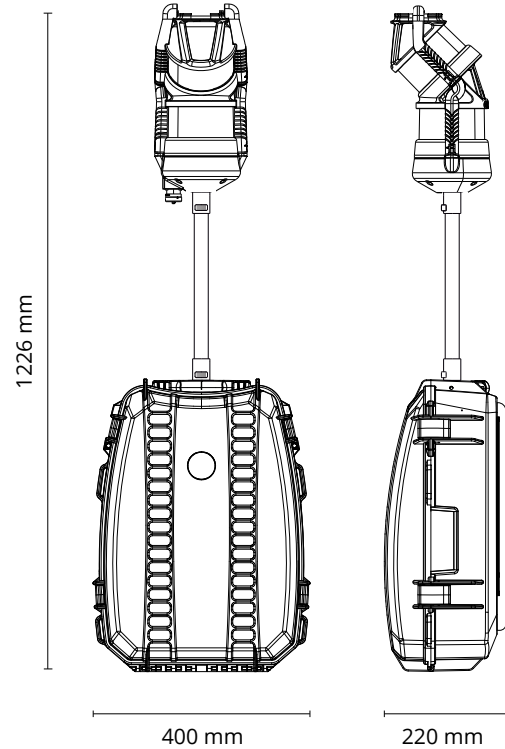
TECH SHEET

MAIN FEATURES

Suitable environment	indoor/outdoor
Handheld	possible ⁽¹⁾
Wearable	yes
Mountable on various mobile platforms (car, trolley, bike, quad, boat, robot)	yes
SLAM post-processing software included (HERON Desktop)	yes
Point cloud advanced processing software included (Reconstructor)	yes
Free software for x-ray maps visualization and measuring included (GoBlueprint)	yes
Output data	.e57, .las, .ply, export to ReCap
Points per second	1,280,000
Local accuracy	±4 mm
Max survey resolution	1 cm
Global accuracy	±4 cm in short close rings ⁽²⁾
Control points acquisition	yes
Global accuracy with control points	±2 cm
Loop closure	not mandatory
Usable in every light conditions	yes
Initialization and calibration procedures	not required
Single operator	yes
Sensors working time (in continuous acquisition)	~ 2 h (more with extra batteries)
Change detection & Automatic self-localization	yes (optional add-on)
Operating temperature	-10° ; +45°
Storage temperature	-40° ; +60°
Rugged transport case	yes

SYSTEM CONTROLLER

Weight and Dimensions	1085 g 160 x 209 x 59 mm
Processor	Intel® 11 th Gen Core™ (4.1 GHz)
• PENDRIVE for data storage	USB 3.1 Gen 1
Memory size	256 GB
Max read speed	up to 300 MB/sec
Max write speed	up to 100 MB/sec
• INTERNAL BATTERY	Li-ion battery
Capacity	6700 mAh 80.4 Wh
Output	12 V
Working time	~ 2 h (more with extra "plug&go" batteries)



CAPTURE HEAD (DETACHABLE)

Weight and Dimensions	2380 g 338 x 141 x 153 mm
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COMPONENTS:

• LASER SENSORS	32+32 chs Class 1 Eye Safe
Laser wavelength	905 nm
Laser range	0.05 - 120 m
FOV	360° x 360° ⁽³⁾
• IMU	yes

PDA CONTROL UNIT

Personal Digital Assistant

Weight and Dimensions	560 g 167 x 81.4 x 15.5 mm
Processor	Helio G95 Octa Core 2.1 GHz
Display	6.22" LCD HD + waterdrop screen
Battery	Li-ion 6350 mAh
Battery charging	24 W Type-C fast charge
Battery working time	15 ÷ 24 h (depending on the display intensity)

TECH SHEET

RUGGED BACKPACK

Dimensions	540 x 400 x 220 mm
Weight	4850 g
Internally cabled	Controller and Capture Head connection
For mapping use	yes
For storage and transport use	yes

SOFTWARE EQUIPMENT

Reconstructor	included
Reconstructor HERON add-on	included
3D navigation of point clouds and images	yes
Automatic scans registration	yes
Direct data import	.laz, .e57, .fls, .zfs, .rxp, .x3s, .x3m, .clr, .cl3, .dp, .ixf, .nctri, .txt, .las, .ptx, .pts, .ptg, .asc, .ply, .csv, DEM Ascii
Point cloud filtering, managing and classifying	yes
Import .ifc BIM format	yes
Import terrestrial laser scanner data	yes
Import point clouds from UAV	yes
Import mobile mapping data	yes
CAD/Mesh models	.3ds, .ifc, .obj, .dxf, .stl, .txt, .wrl, .vrml, .ply, .mvx, .dae
Direct export	ReCap, Geo-Plus, Cintoo, ObitGT, 3DUserNet
Cross sections and profiles (.dxf)	yes
Orthophotos & x-ray orthophotos (direct export to AutoCAD)	yes
Volumes and areas computation	yes
Mesh creation and manipulation	yes
Verification tool	yes

OPTIONAL TOOLKITS

Extra batteries	standard "plug&go" ~ 2 h 445 g
	high-capacity "plug&go" ~ 4 h 860 g
Telescopic pole	from 560 to 1800 mm 1000 g
Centering tip	150 mm 12 g
Ring LED Light	Ø126 x 184 mm 700 g 4000 lm 36 W
Car mount	(with case) 547 x 427 x 251 mm 9000 g

HERON Desktop	included
Drift effect reducing (global optimization)	yes
3D local maps patented algorithm	yes
Large coordinates for geolocalization	yes
Split/merge trajectories and point clouds	yes
Automatic post-processing mode	yes
Noise cleaning (attenuation)	yes
Moving objects removing	yes

GoBlueprint	free software
Volume calculation based on x-ray maps	yes
Measures on x-ray maps directly (lines, angles, areas)	yes
For any Windows-based PC and tablet (to bring your maps on-site too)	yes
Deliverables easy to manage and share	yes

HERON Constraints tool	included
HERON Tracking add-on	optional
Reconstructor MINING add-on	optional
Reconstructor COLOR add-on	optional
Reconstructor 3D Viewer	free tool
ClearEdge3D EdgeWise	optional
ClearEdge3D Verity & Rithm	optional
3DUserNet VISION (discount rates available)	optional
Cintoo Cloud	optional

(1) When needed, it is possible to use the capture head with telescopic poles, to easily map hidden areas such as holes, ravines, manholes, etc.

(2) The global accuracy depends on the effectiveness of the SLAM registration algorithm, which can be influenced by the geometry of the surveyed environment. Long trajectories in absence of loop closures and cross paths, such as narrow tunnels or narrow stairs, can downgrade the global accuracy to 5-10 cm. The patented and unique algorithms present in HERON Desktop and the use of control points or control scans as constraints can dramatically improve the quality of the global accuracy up to 2 cm. The Gexcel support team is always available to provide you with more detailed information on this topic.

(3) Final FOV guaranteed by walking with the system.

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